

Measure Theory and Applications to Probability and Signal Filtering

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The downsides of the Riemann Integral

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The downsides of the Riemann Integral

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- Define $f : [0, 1] \rightarrow \mathbb{R}$

$$f(x) = \begin{cases} 1 & x \in \mathbb{Q} \\ 0 & x \notin \mathbb{Q} \end{cases}$$

- When one uses the definition for Riemann Integrability we find $L(f, P, [0, 1]) = 0$ and $U(f, P, [0, 1]) = 1$ which implies $f(x)$ is not Riemann Integrable.

Length of Intervals

- How can we get the length of an interval?
- Definition: The length $L(I)$ of an open interval I is defined by

$$L(I) = \begin{cases} b-a & \text{if } I = (a, b) \text{ for some } a, b \in \mathbb{R} \text{ with } a \leq b \\ 0 & \text{if } I = \emptyset \\ \infty & \text{if } I = (-\infty, a) \text{ or } I = (a, \infty) \text{ for some } a \in \mathbb{R} \\ \infty & \text{if } I = (-\infty, \infty) \end{cases}$$

Using length to define Outer Measure

Definition:

The outer measure of $|A|$ of a set $A \subset \mathbb{R}$ is defined by

$$|A| = \inf \left\{ \sum_{k=1}^{\infty} L(I_k) : I_1, I_2, \dots \text{ are open intervals such that } A \subset \bigcup_{k=1}^{\infty} I_k \right\}$$

Heine-Borel Theorem

Definition:

Suppose $A \subset \mathbb{R}$ then call the collection \mathcal{C} of open subsets of \mathbb{R} an open cover of A if A is contained in the union of all the sets in \mathcal{C} . \mathcal{C} has a finite subcover of A if A is contained in a finite list of sets in \mathcal{C} .

Heine-Borel Theorem:

Every open cover of a bounded closed subset of \mathbb{R} has a finite subcover.

Important Properties of Outer Measure

- Countable subsets of \mathbb{R} have outer measure 0!
- Outer Measure preserves order, i.e let A and B be subsets of \mathbb{R} such that $A \subset B$ then $|A| \leq |B|$
- Outer Measure is translation invariant! That is if $t \in \mathbb{R}$ and $A \subset \mathbb{R}$ then $t + A = \{ t + a : a \in A \}$ then $|t + A| = |A|$
- There always exists disjoint subsets of A and B of \mathbb{R} such that $|A \cup B| \neq |A| + |B|$

Applications of Outer Measure

- On a closed interval, $a, b \in \mathbb{R}$, $a \leq b$, then $|[a, b]| = b - a$. Done with Heine-Borel Theorem.
- Every interval in \mathbb{R} containing at least two distinct elements is uncountable.
- Originally shown by Georg Cantor, but with a very lofty proof, the proof for this is much simpler.

Definition: σ -Algebras

Let X be a set and \mathcal{S} be a set of subsets of X . Then \mathcal{S} is considered a σ -Algebra if:

- $\emptyset \in \mathcal{S}$
- if $E \in \mathcal{S}$ then $X \setminus E \in \mathcal{S}$
- if E_1, E_2, \dots is a sequence of events in \mathcal{S} then $\bigcup_{k=1}^{\infty} E_k \in \mathcal{S}$

σ -Algebras closed under countable intersection

Suppose \mathcal{S} is a σ -Algebra on X . Then,

- $X \in \mathcal{S}$
- if $D, E \in \mathcal{S}$, then $D \cup E \in \mathcal{S}$ and $D \cap E \in \mathcal{S}$ and $D \setminus E \in \mathcal{S}$
- if E_1, E_2, \dots is a sequence of events in \mathcal{S} then $\bigcap_{k=1}^{\infty} E_k \in \mathcal{S}$

Measurable Spaces

Definition: Measurable Spaces and Sets

- A measurable space is simply an ordered pair (X, \mathcal{S}) where X is a set and \mathcal{S} is a σ -Algebra on X .
- An event in \mathcal{S} is called an \mathcal{S} -measurable set

Borel Sets

Smallest σ -algebra

If X is a set and \mathcal{A} is a set of subsets of X , then the intersection of σ -algebras on X that contain \mathcal{A} is also a σ -algebra on X .

Definition: Borel Set

The smallest σ -algebra on \mathbb{R} containing all open subsets of \mathbb{R} is called the collection of Borel subsets of \mathbb{R} . Any element of this σ -algebra is called a Borel Set.

- A subset $[-\infty, \infty]$ is called a Borel set
- Every closed subset of \mathbb{R} is a Borel set since every closed subset of \mathbb{R} is the complement of an open subset of \mathbb{R}
- Every countable subset of \mathbb{R} is a Borel set, to see this let a set $A = x_1, x_2, \dots$ then $B = \bigcup_{k=1}^{\infty} \{x_k\}$ is a Borel set since each $\{x_k\}$ is closed
- If $f : \mathbb{R} \rightarrow \mathbb{R}$ any set of points where f is continuous is the intersection of open sets and thus a Borel set

Inverses and their Properties

Definition: Inverse Images

If $f : X \rightarrow Y$ is a function and $A \subset Y$ then the set $f^{-1}(A)$ is defined by,

$$f^{-1}(A) = \{x \in X : f(x) \in A\}$$

Properties of Inverses

- Suppose $f : X \rightarrow Y$ and $g : Y \rightarrow W$ are functions, then

$$(g \circ f)^{-1}(A) = f^{-1}(g^{-1}(A)) \text{ for every } A \subset W$$

- Suppose $f : X \rightarrow Y$, then

- $f^{-1}(Y \setminus A) = X \setminus f^{-1}(A)$ for every $A \subset Y$
- $f^{-1}(\cup_{A \in \mathcal{A}} A) = \cup_{A \in \mathcal{A}} f^{-1}(A)$ for every set \mathcal{A} of subsets of \mathcal{Y}
- $f^{-1}(\cap_{A \in \mathcal{A}} A) = \cap_{A \in \mathcal{A}} f^{-1}(A)$ for every set \mathcal{A} of subsets of \mathcal{Y}

Measurable Functions and their Conditions

Definition: Measurable Functions

Suppose (X, \mathcal{S}) is a measurable space then the function $f : X \rightarrow \mathbb{R}$ is called \mathcal{S} -measurable if $f^{-1}(B) \in \mathcal{S}$ for every Borel set $B \in \mathbb{R}$

Definition: Borel Measurable Function

Suppose $X \subset \mathbb{R}$, a function $f : X \rightarrow \mathbb{R}$ is called Borel Measurable if $f^{-1}(B)$ is a Borel set for every Borel set $B \subset \mathbb{R}$

- Every continuous function is Borel measurable!

Definition: Measure

Suppose X is a set and \mathcal{S} is a σ -algebra on X . A measure on (X, \mathcal{S}) is a function $\mu : \mathcal{S} \rightarrow [0, \infty]$ such that $\mu(\emptyset) = 0$ and

$$\mu\left(\bigcup_{k=1}^{\infty} E_k\right) = \sum_{k=1}^{\infty} \mu(E_k)$$

for every disjoint sequence E_1, E_2, \dots of sets in \mathcal{S}

Properties of Measure

Definition: Measure Space

A measure space is the ordered triple (X, \mathcal{S}, μ) where X is a set \mathcal{S} is a σ -algebras on X , and μ is a measure on (X, \mathcal{S})

Properties of Measure

- Measure preserves order, $(D \subset E)$ then $\mu(D) \leq \mu(E)$
- (X, \mathcal{S}, μ) is a measure space and $E_1, E_2, \dots \in \mathcal{S}$. Then, $\mu(\cup_{k=1}^{\infty} E_k) \leq \sum_{k=1}^{\infty} \mu(E_k)$
- $\mu(D \cup E) = \mu(D) + \mu(E) - \mu(D \cap E)$, $\mu(D \cap E) \leq \infty$

Connection Between Outer Measure and Lebesgue Measure

Outer Measure and Lebesgue Measure

Outer measure is a measure on $(\mathbb{R}, \mathcal{B})$ where \mathcal{B} is a σ -algebra of Borel subsets of \mathbb{R}

Definition: Lebesgue Measure

Lebesgue measure is the measure on $(\mathbb{R}, \mathcal{B})$ where \mathcal{B} is the σ -algebra that assigns each Borel set to its outer measure.

Definition: Lebesgue Measurable Set

A set $A \subset \mathbb{R}$ is called Lebesgue measurable if there exists a Borel set $B \subset A$ such that $|A \setminus B| = 0$ is the measure on $(\mathbb{R}, \mathcal{B})$ where \mathcal{B} is the σ -algebra that assigns each Borel set to its outer measure.

Convergence of Measurable Functions

Definition: Pointwise and Uniform Convergence

Let X be a set with f_1, f_2, \dots being a sequence of functions from X to \mathbb{R} and f is a function from X to \mathbb{R} .

- The sequence f_1, f_2, \dots converges pointwise on X to f if $\lim_{k \rightarrow \infty} f_k(x) = f(x)$
- The sequence f_1, f_2, \dots converges uniformly on X to f if for every $\epsilon > 0$ there exists a $n \in \mathbb{Z}^+$ such that $|f_k(x) - f(x)| < \epsilon$ for all integers $k \geq n$ and all $x \in X$

Simple Functions and Approximations with them

- A function is simple if it takes only finitely many values
- We can approximate functions by simple functions!
 - Let each f_k be a simple \mathcal{S} -measurable function
 - $|f_k(x)| \leq |f_{k+1}(x)| \leq |f(x)|$ for all $k \in \mathbb{Z}^+$ and all $x \in X$
 - $\lim_{k \rightarrow \infty} f_k(x) = f(x)$ for every $x \in X$
 - f_1, f_2, \dots converges uniformly on X to f if f is bounded!

Integration with respect to a Measure

Integral in terms of simple functions

Let (X, \mathcal{S}, μ) be a measure space and $f : X \rightarrow [0, \infty]$ is \mathcal{S} -measurable, then

$$\int f d\mu = \sup\left\{ \int s d\mu : s \text{ simple } 0 \leq s \leq f \right\}$$

Properties of Integration

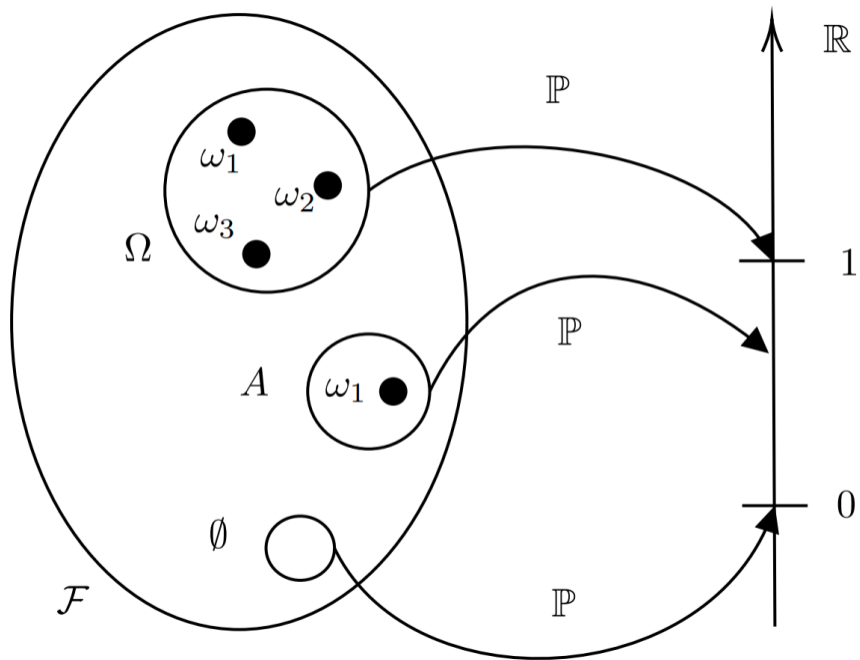
Suppose (X, \mathcal{S}, μ) is measure space and $f, g : X \rightarrow [0, \infty]$ are \mathcal{S} -measurable functions

- Integration preserves order! s.t $f(x) \leq g(x)$ for all $x \in X$ then $\int f d\mu \leq \int g d\mu$
- Additivity, $\int (f + g) d\mu = \int f d\mu + \int g d\mu$
- Can break function, $X \rightarrow [-\infty, \infty]$, into its positive and negative regions and take difference to integrate real valued functions
- Homogeneous, $\int c f d\mu = c \int f d\mu$
- Absolute Value, $|\int f d\mu| \leq \int |f| d\mu$

Probability Measures and Spaces

What is a probability measure?

- Suppose \mathcal{F} is a σ -algebra on a set Ω , then a probability measure on (Ω, \mathcal{F}) is a measure P on (Ω, \mathcal{F}) such that $P(\Omega) = 1$
- Ω is called the sample space
- An event is an element of \mathcal{F}
- Given an event A , $P(A)$ is called the probability of A
- If P is the probability measure on (Ω, \mathcal{F}) then (Ω, \mathcal{F}, P) is called the probability space



Independence and Conditional Probability

Independent Events

Suppose (Ω, \mathcal{F}) then (Ω, \mathcal{F}, P) is the probability space,

- Two events, A and B, are independent if $P(A \cap B) = P(A) \cdot P(B)$
- For more than two events, $P(A_{k_1} \cup A_{k_2} \cup \dots A_{k_n}) = P(A_{k_1}) \dots P(A_{k_n})$ for k_1, \dots, k_n

Conditional Probability

Suppose (Ω, \mathcal{F}, P) is a probability space and B is an event with $P(B) > 0$. Can define $P_B : \mathcal{F} \rightarrow [0, 1]$ by

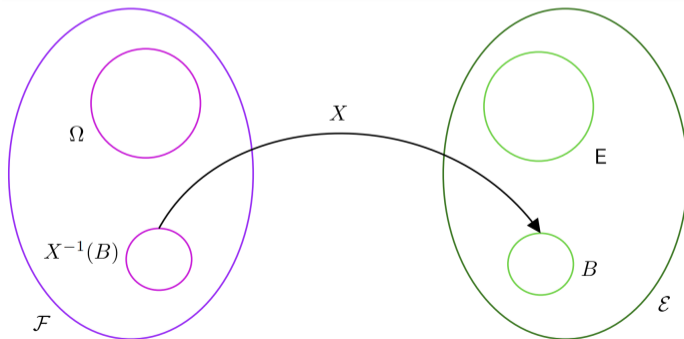
$$P_B(A) = P(A|B) = \frac{P(A \cap B)}{P(B)}$$

If $A \in \mathcal{F}$, then $P_B(A)$ is called the conditional probability of A given B.

Random Variables

How random is random?

- A random variable can be discrete or continuous, but in either case is a function that maps from $\Omega \rightarrow \mathbb{R}$
- A variable that depends on the outcome of a random process



Probability Distribution and Distribution Function

Suppose (Ω, \mathcal{F}, P) is a probability space and X is a random variable.

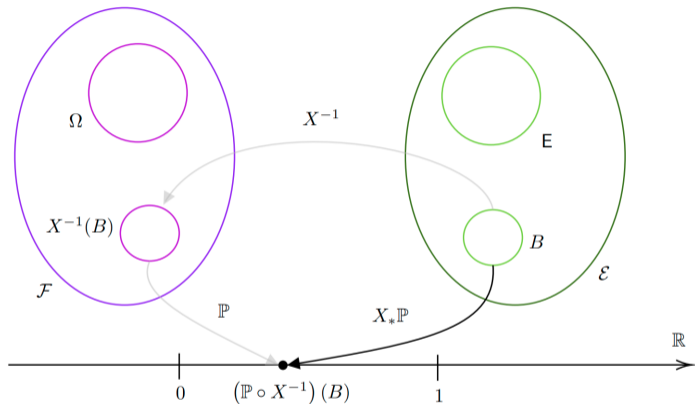
Probability Distribution

The probability distribution of X is the probability measure P_X defined on $(\mathbb{R}, \mathcal{B})$ by $P_X(B) = P(X \in B) = P(X^{-1}(B))$

Distribution Function

The distribution function of X is the function $\tilde{X} = P_X((-\infty, s]) = P(X \leq s)$

Measure to define probability





Nice Properties

- Using measure we can define expectation, independence, variance and standard deviation of random variables
- Everything we use already in probability!

Applications to Signal Filtering

- Measure is the foundation of stochastic calculus, Ito's Formula, Stratonovich's Integral, and stochastic flow
- Can create filtering equations (Zakai) based on stochastic calculus
- Kalman-Bucy filtering, i.e. continuous Kalman filter!
- What are the limitations of this filtering in this way?

References

-  Shelton Axler (2019)
Measure, Integration Real Analysis
-  Jie Xiong (2008)
An Introduction to Stochastic Filtering Theory

The End